

Constructing Separators and Adjustment Sets in Ancestral Graphs

Benito van der Zander, Maciej Liśkiewicz, Johannes Textor



Universität zu Lübeck

Utrecht University

Motivation

- Given any causal graph G , any set of exposures \mathbf{X} and any set of outcomes \mathbf{Y} we want to calculate the causal effect of \mathbf{X} on \mathbf{Y} with a statistically well understood and robust method.
- Standard technique is to use a set \mathbf{Z} of covariate adjustments such that the causal effect is given by

$$\sum_z p(y | x, z)p(z)$$

- How can we test, find or enumerate all (minimal/minimum) adjustment sets?

Overview

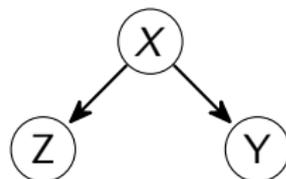
- ① Motivation
- ② Previous Work
- ③ Adjustment criterions
- ④ Algorithms
- ⑤ Generalization
 - Ancestral graphs
 - Maximal ancestral graphs

Previous Work

- Backdoor criterion [Pea09]
- Frontdoor criterion [Pea09]
- Do-calculus [Pea09]
- Adjustment criterion [Shp12]

Previous Work

- Backdoor criterion [Pea09]
Not complete
- Frontdoor criterion [Pea09]
- Do-calculus [Pea09]
- Adjustment criterion [Shp12]



Previous Work

- Backdoor criterion [Pea09]
Not complete
- Frontdoor criterion [Pea09]
Not complete, uncertain statistical properties
- Do-calculus [Pea09]
- Adjustment criterion [Shp12]

Previous Work

- Backdoor criterion [Pea09]
Not complete
- Frontdoor criterion [Pea09]
Not complete, uncertain statistical properties
- Do-calculus [Pea09]
Uncertain statistical properties
- Adjustment criterion [Shp12]

Previous Work

- Backdoor criterion [Pea09]
Not complete
- Frontdoor criterion [Pea09]
Not complete, uncertain statistical properties
- Do-calculus [Pea09]
Uncertain statistical properties
- Adjustment criterion [Shp12]
Not directly applicable in algorithms

Method

- Reduce adjustment to d-separation
- Use d-separation algorithms

Adjustment in DAGs: criterion

Theorem (Adjustment criterion, simplifying [SVR10, Shp12])

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

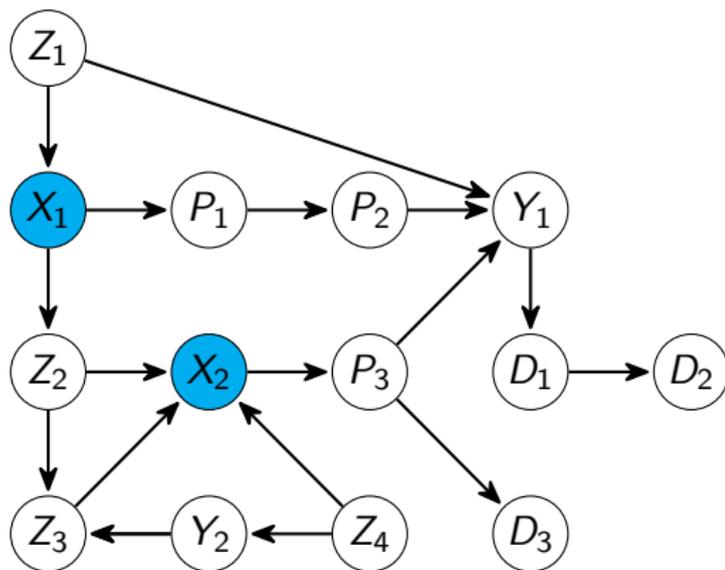
“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{Z} exactly once

Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

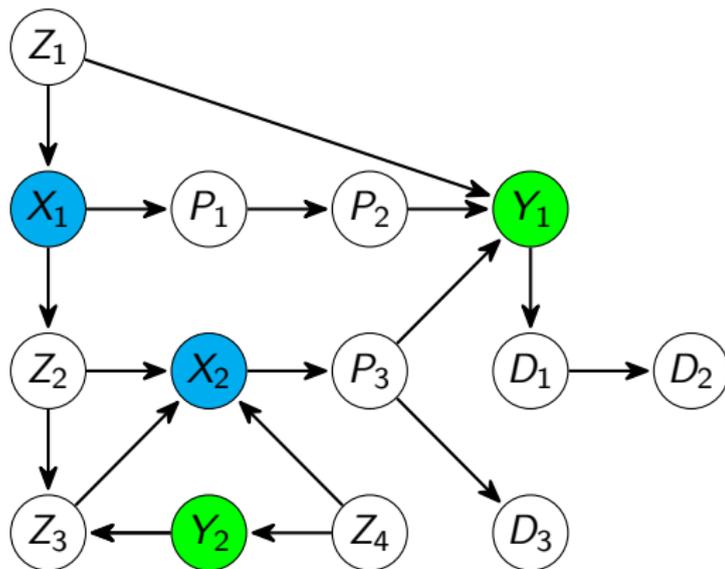


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\leftarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

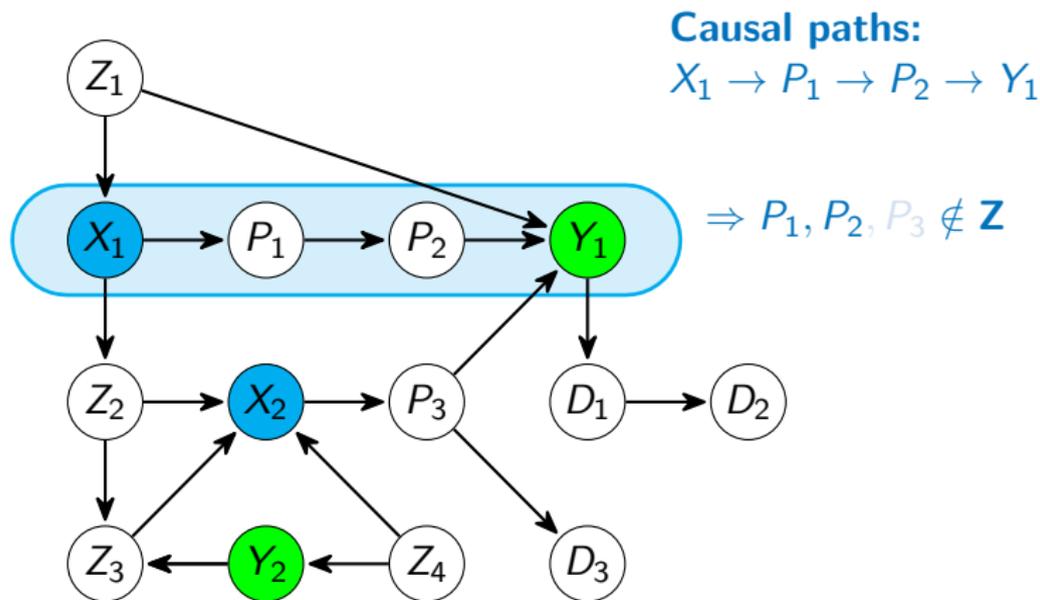


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

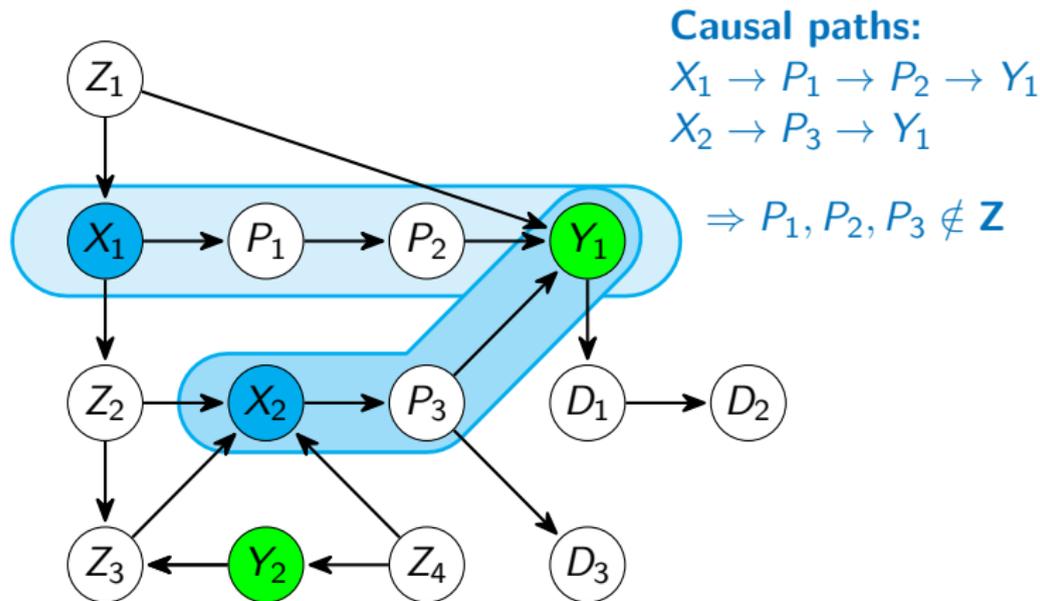


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

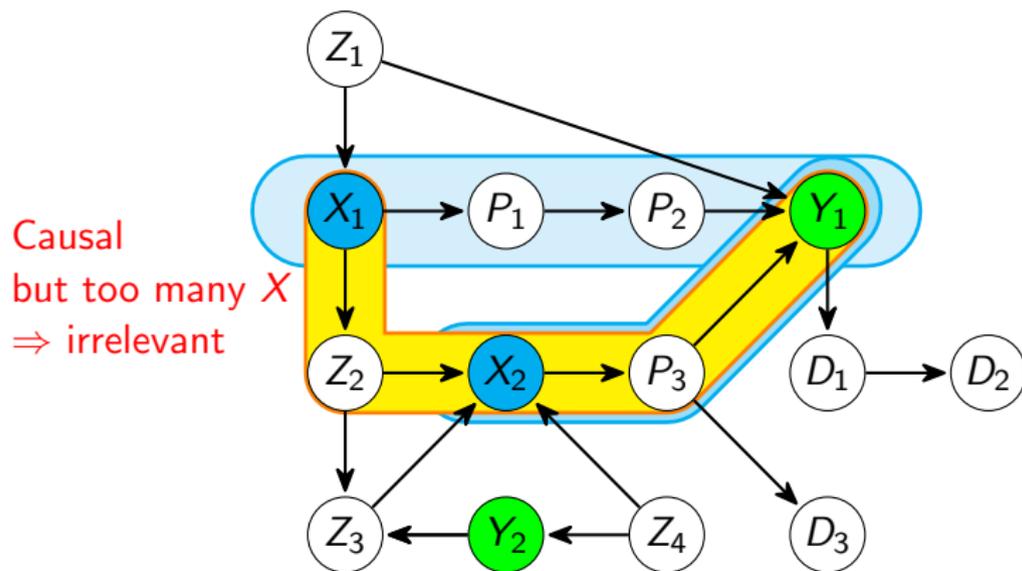


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once



Adjustment in DAGs: example

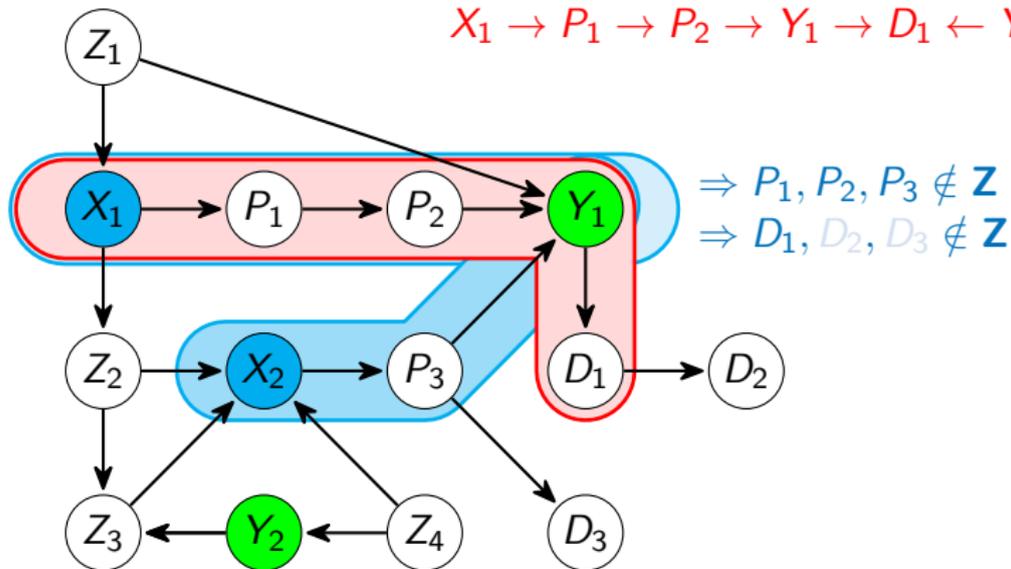
A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

Possible noncausal paths:

$X_1 \rightarrow P_1 \rightarrow P_2 \rightarrow Y_1 \rightarrow D_1 \leftarrow Y_1$



Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

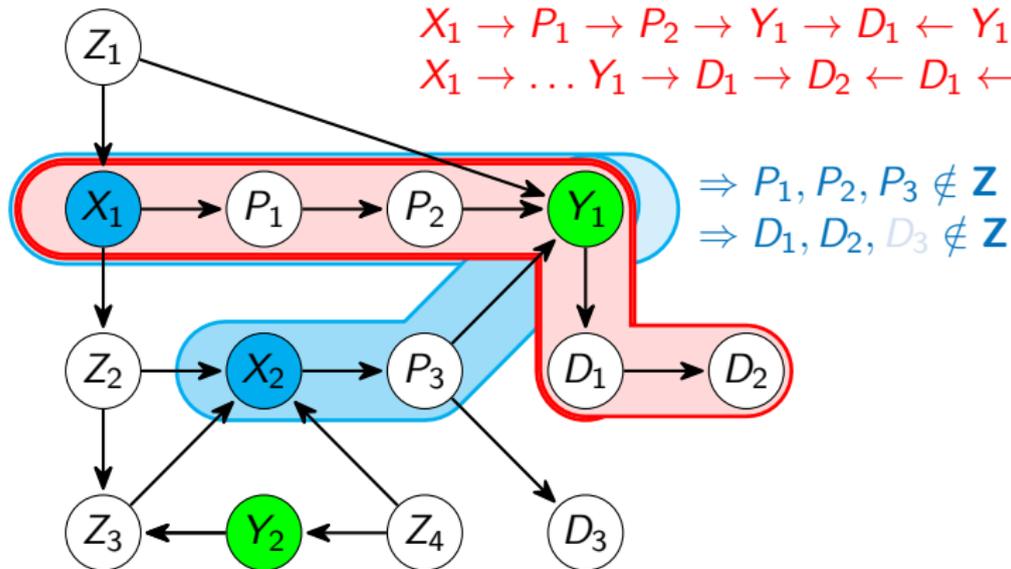
- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

Possible noncausal paths:

$X_1 \rightarrow P_1 \rightarrow P_2 \rightarrow Y_1 \rightarrow D_1 \leftarrow Y_1$

$X_1 \rightarrow \dots Y_1 \rightarrow D_1 \rightarrow D_2 \leftarrow D_1 \leftarrow Y_1$

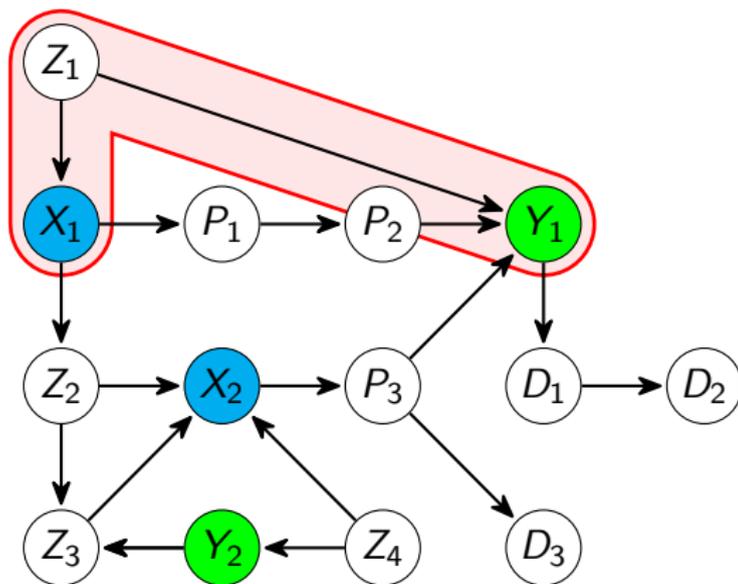


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

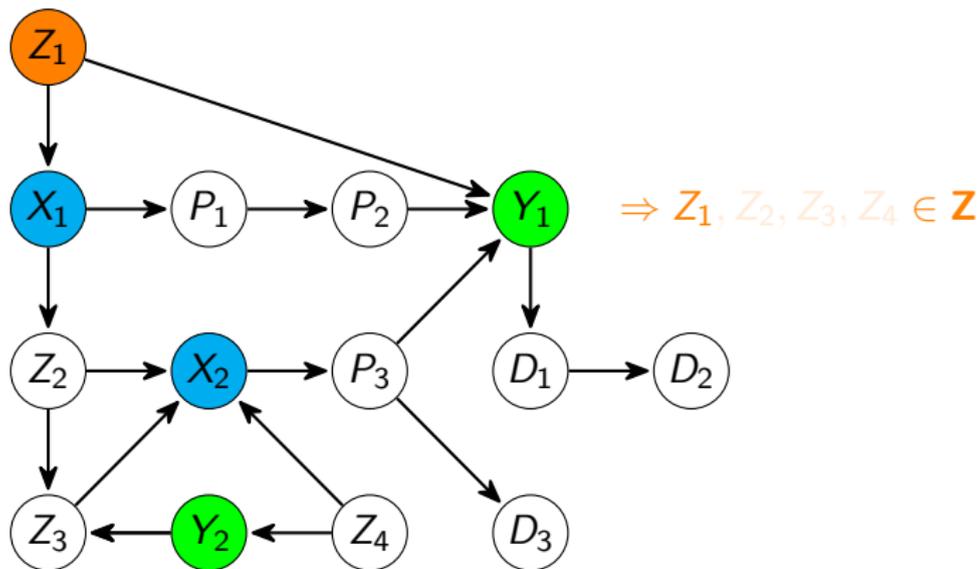


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\leftarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

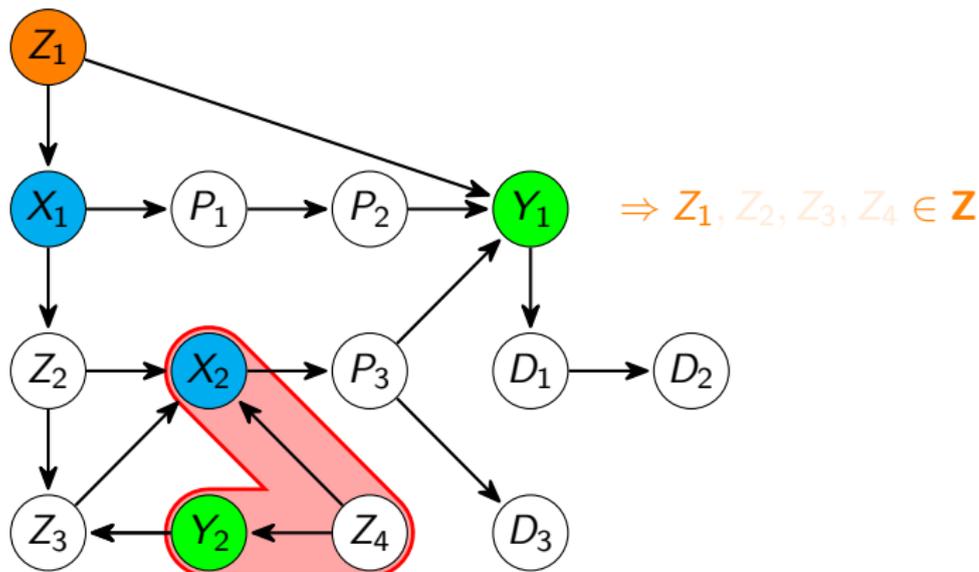


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\leftarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

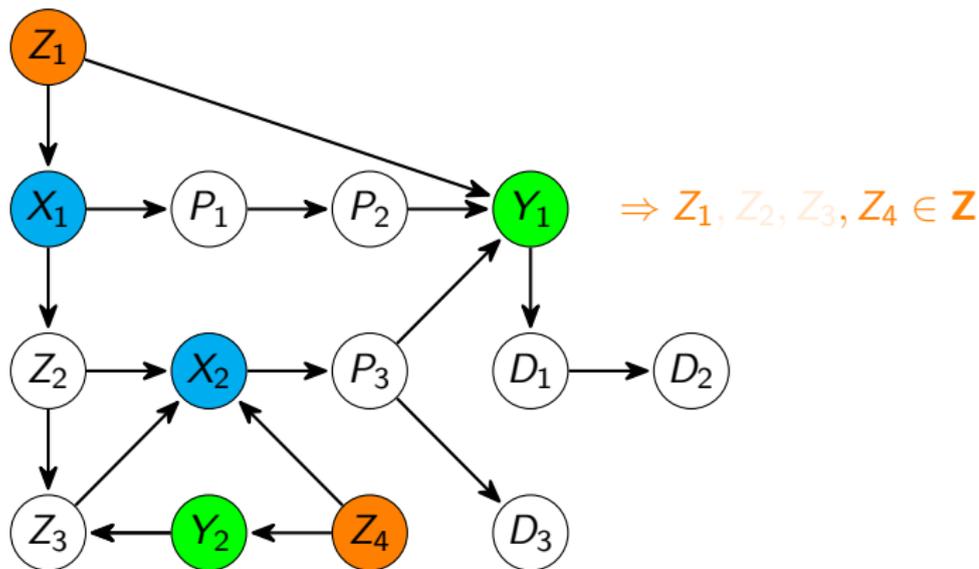


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\leftarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

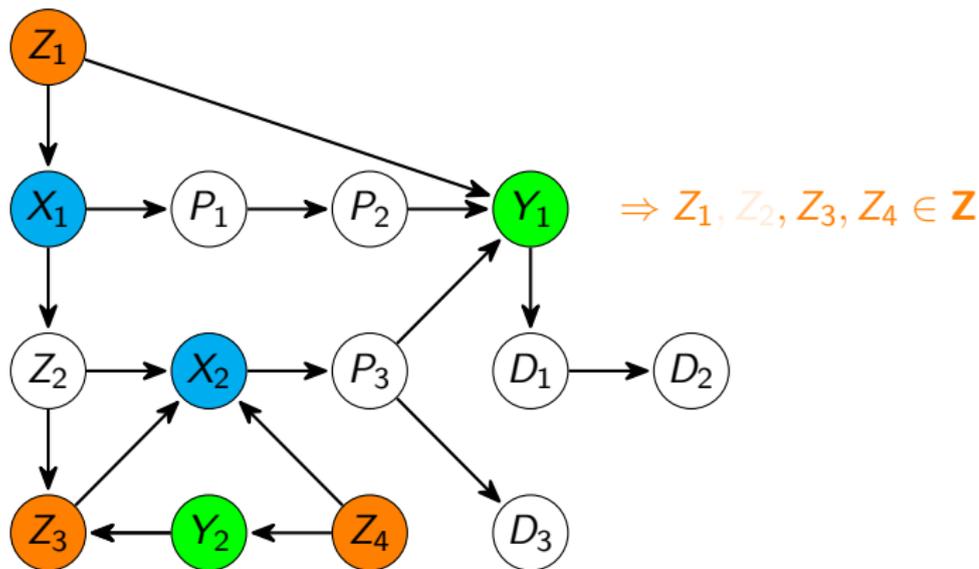


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\leftarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

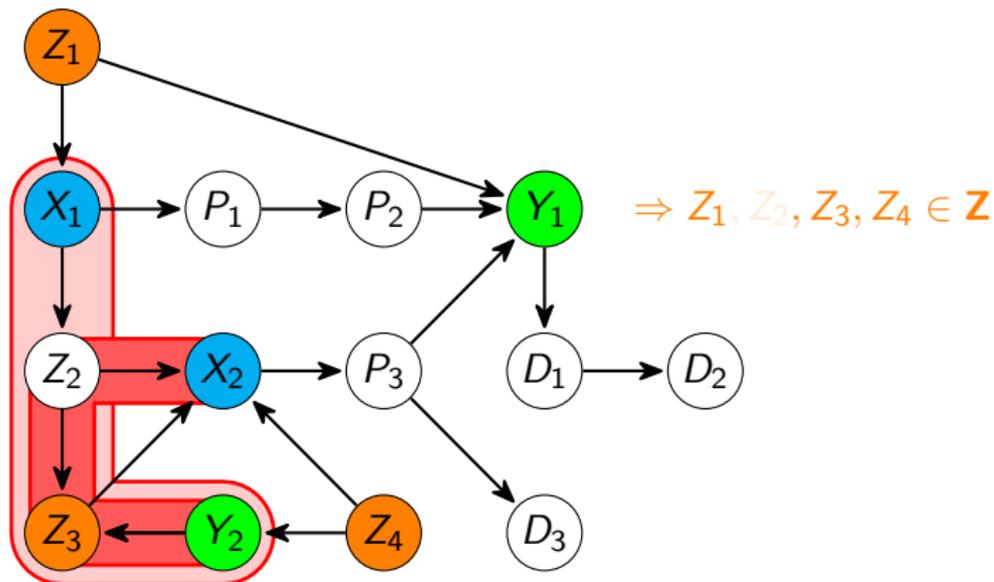


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

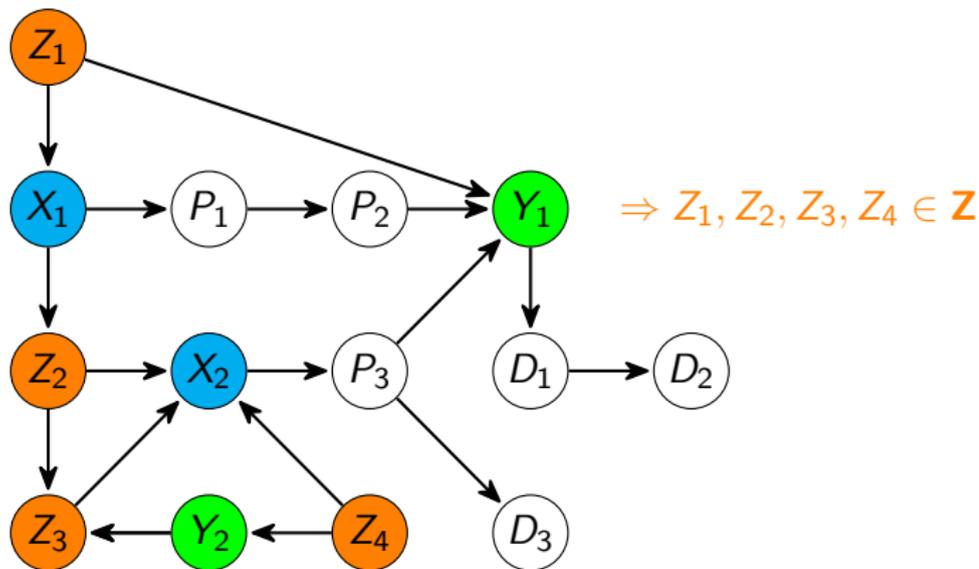


Adjustment in DAGs: example

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\leftarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once



Adjustment in DAGs: criterion

Theorem (Adjustment criterion, simplifying [SVR10, Shp12])

A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} does not block any causal path and $\mathbf{X}(\rightarrow, \rightarrow\rightarrow, \dots)\mathbf{Y}$
- 2 \mathbf{Z} blocks all non-causal paths $\mathbf{X}(\leftarrow, \leftarrow\rightarrow, \rightarrow\leftarrow, \dots)\mathbf{Y}$

“path”: d-walk from \mathbf{X} to \mathbf{Y} that intersects \mathbf{X} exactly once

Theorem (New adjustment criterion)

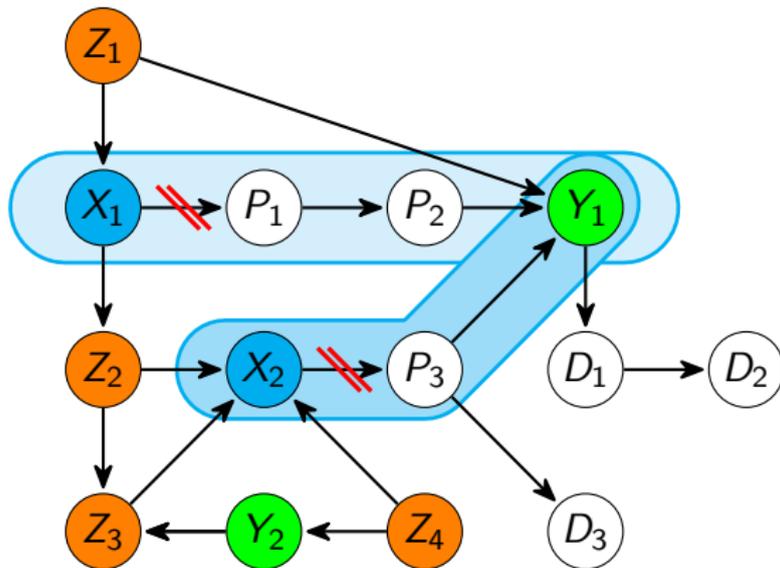
A set \mathbf{Z} is an adjustment relative to sets \mathbf{X} and \mathbf{Y} if and only if:

- 1 \mathbf{Z} neither contain nodes of causal paths nor their descendants and
- 2 \mathbf{Z} separates \mathbf{X} and \mathbf{Y} in a modified graph without causal paths

Adjustment in DAGs: example

A set Z is an adjustment relative to sets X and Y if and only if:

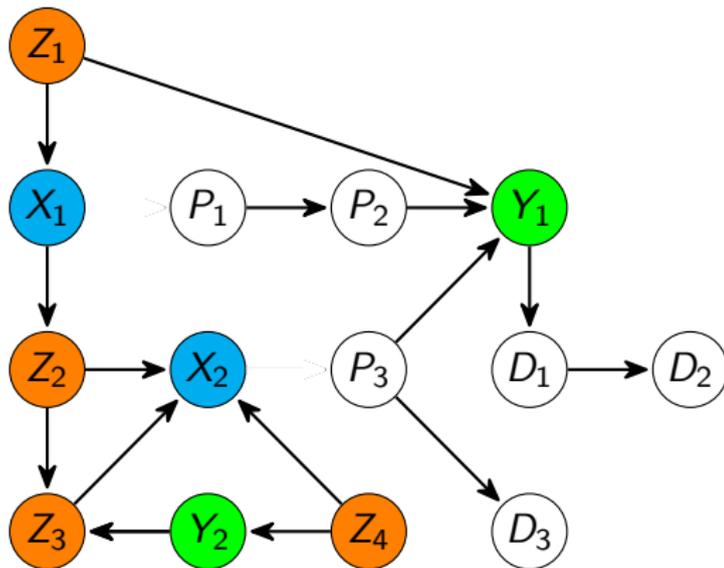
- 1 Z neither contain nodes of causal paths nor their descendants and
- 2 Z separates X and Y in a modified graph without causal paths



Adjustment in DAGs: example

A set Z is an adjustment relative to sets X and Y if and only if:

- 1 Z neither contain nodes of causal paths nor their descendants and
- 2 Z separates X and Y in a modified graph without causal paths



Algorithms for d-separation

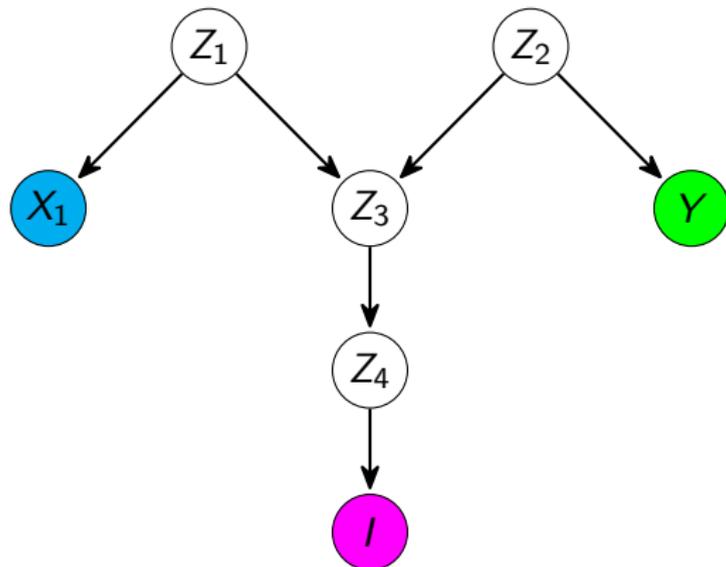
Need to generalize existing separation algorithms to

- support sets $|\mathbf{X}| > 1$
- find only \mathbf{Z} restricted to $\mathbf{Z} \subseteq \mathbf{R}$
- (find only \mathbf{Z} containing $\mathbf{I} \subseteq \mathbf{Z}$ to enumerate them all)

Algorithms for d-separation: Ideas

Finding any separators

Ancestors of \mathbf{X} , \mathbf{Y} , \mathbf{I} are separator or none exists

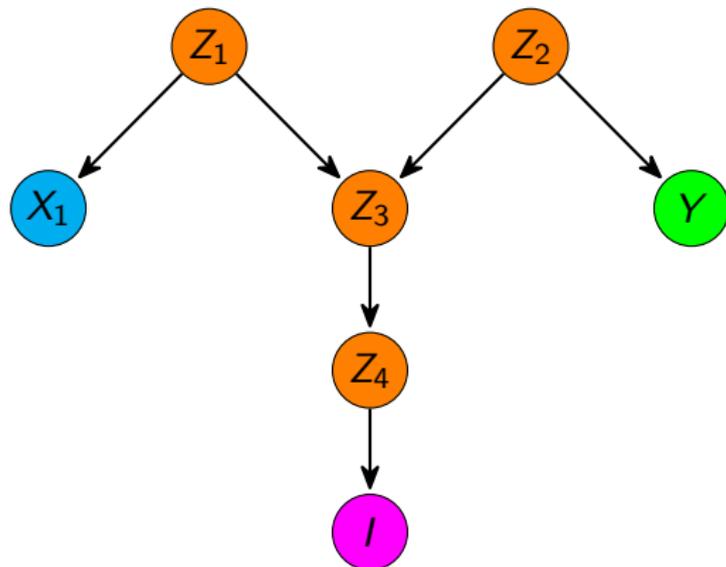


$O(n + m)$

Algorithms for d-separation: Ideas

Finding any separators

Ancestors of \mathbf{X} , \mathbf{Y} , \mathbf{I} are separator or none exists



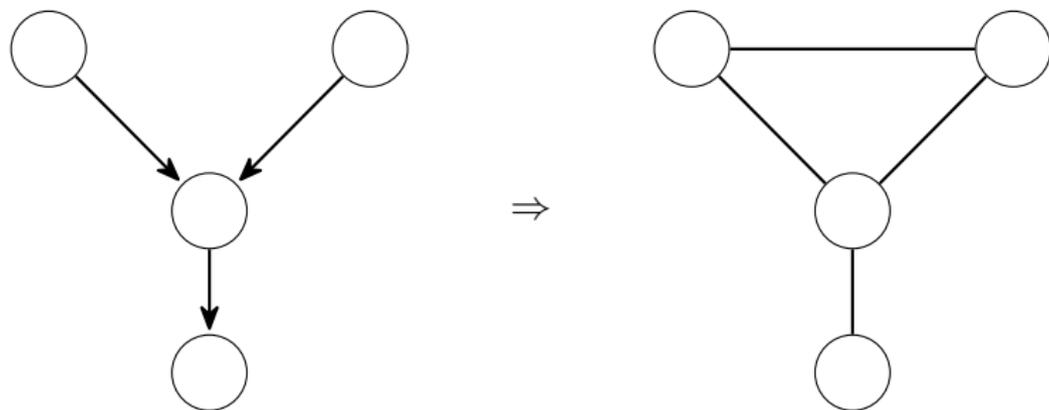
$O(n + m)$

Algorithms for d-separation: Ideas

Finding minimal separators, generalizing [AdC96, TPP98, RS02]

Moralization:

“Marry” parents to create undirected graph:



Find minimal vertex cut with standard search

Find minimum vertex cut with min-cut-max-flow.

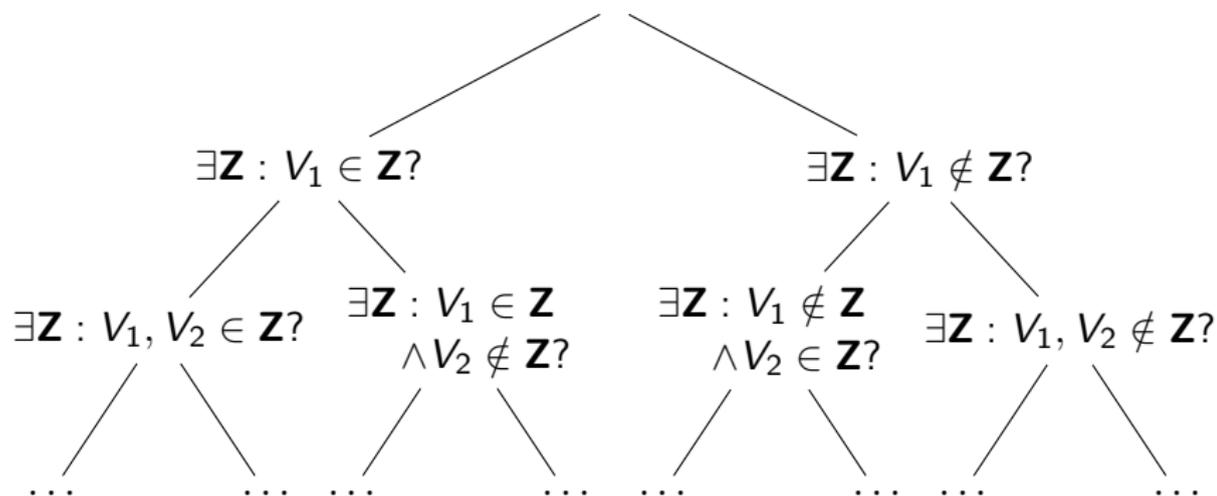
$O(n^2)$

$O(n^3)$

Algorithms for d-separation: Ideas

Enumerating all separators, idea from [Tak10, TL11]

Prune search tree:

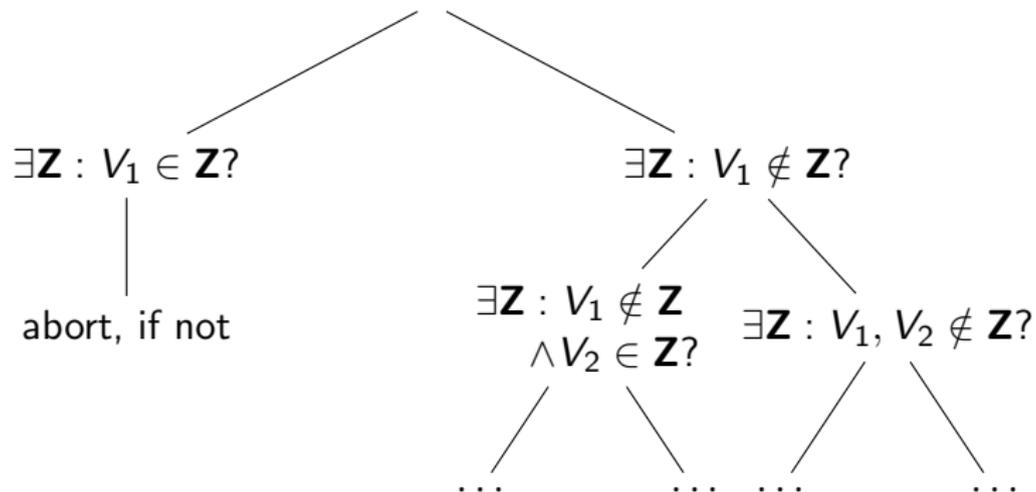


$O(n^3)$ delay

Algorithms for d-separation: Ideas

Enumerating all separators, idea from [Tak10, TL11]

Prune search tree:

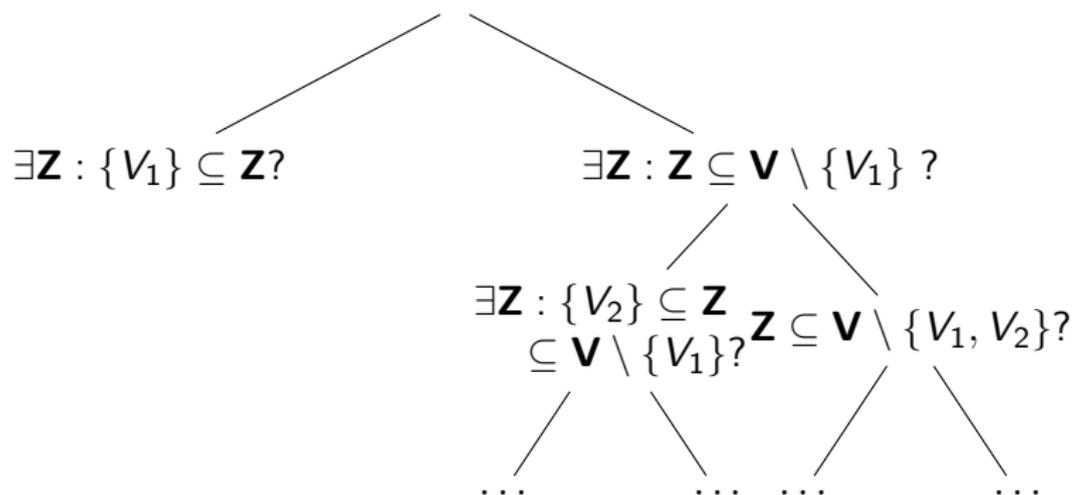


$O(n^3)$ delay

Algorithms for d-separation: Ideas

Enumerating all separators, idea from [Tak10, TL11]

Prune search tree:



$O(n^3)$ delay

Algorithms for adjustments

Verification: For given \mathbf{X} , \mathbf{Y} and \mathbf{Z} decide if ...

TESTADJ \mathbf{Z} is an adjustment to \mathbf{X} , \mathbf{Y} $\mathcal{O}(n + m)$

TESTMINADJ \mathbf{Z} is an adjustment to \mathbf{X} , \mathbf{Y} but no $\mathbf{Z}' \subsetneq \mathbf{Z}$ does $\mathcal{O}(n^2)$

Construction: For given \mathbf{X} , \mathbf{Y} and auxiliary \mathbf{I} , \mathbf{R} , output ...

FINDADJ an adjustment \mathbf{Z} with $\mathbf{I} \subseteq \mathbf{Z} \subseteq \mathbf{R}$ $\mathcal{O}(n + m)$

FINDMINADJ a minimal adjustment \mathbf{Z} with $\mathbf{I} \subseteq \mathbf{Z} \subseteq \mathbf{R}$ $\mathcal{O}(n^2)$

FINDMINCOSTADJ a minimum-cost adjustment \mathbf{Z} with $\mathbf{I} \subseteq \mathbf{Z} \subseteq \mathbf{R}$ $\mathcal{O}(n^3)$

Enumeration: For given \mathbf{X} , \mathbf{Y} , \mathbf{I} , \mathbf{R} enumerate all ...

LISTADJ adjustments \mathbf{Z} with $\mathbf{I} \subseteq \mathbf{Z} \subseteq \mathbf{R}$ $\mathcal{O}(n(n + m))$ delay

LISTMINADJ minimal adjustments \mathbf{Z} with $\mathbf{I} \subseteq \mathbf{Z} \subseteq \mathbf{R}$ $\mathcal{O}(n^3)$ delay

Generalization

Ancestral graphs

Generalized DAGs with additional $-$ and \leftrightarrow edges:

$X - Y$ similar to $X \rightarrow S \leftarrow Y$

$X \leftrightarrow Y$ similar to $X \leftarrow L \rightarrow Y$

Generalization

Ancestral graphs

Generalized DAGs with additional $-$ and \leftrightarrow edges:

$X - Y$ similar to $X \rightarrow S \leftarrow Y$

$X \leftrightarrow Y$ similar to $X \leftarrow L \rightarrow Y$

\Rightarrow Separation algorithms can be used

Generalization

Maximal ancestral graphs (MAGs)

- MAGs are used, when not all causal variables are known.
- All non separable nodes must be adjacent.
- Multiple DAGs G can be represented by a single MAG $G_{\mathbf{S}}^{\mathbf{L}}$.

Example

MAG: $G_{\mathbf{S}}^{\mathbf{L}} = X \rightarrow Y$

Represents among others DAGs:

$G_1 = X \rightarrow Y$ with $\mathbf{L} = \mathbf{S} = \emptyset$

$G_2 =$  with $\mathbf{L} = L, \mathbf{S} = \emptyset$

- \mathbf{Z} is an adjustment in MAG $G_{\mathbf{S}}^{\mathbf{L}}$, if (and only if) it is an adjustment in every represented DAG G

Generalization

Maximal ancestral graphs (MAGs)

- MAGs are used, when not all causal variables are known.
- All non separable nodes must be adjacent.
- Multiple DAGs G can be represented by a single MAG $G_{\mathbf{S}}^{\mathbf{L}}$.

Example

MAG: $G_{\mathbf{S}}^{\mathbf{L}} = X \rightarrow Y$

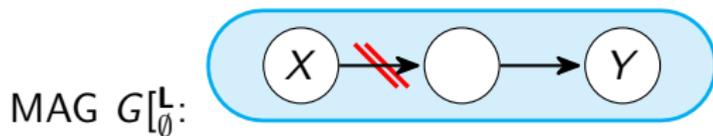
Represents among others DAGs:

$$G_1 = X \rightarrow Y \quad \text{with } \mathbf{L} = \mathbf{S} = \emptyset$$

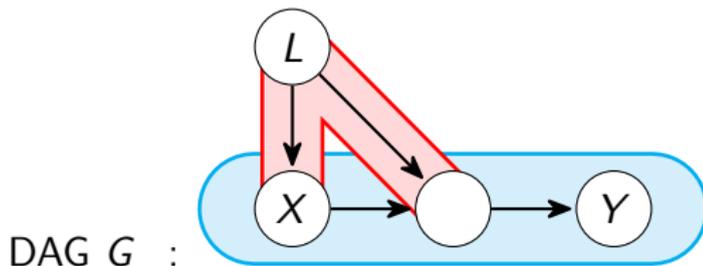
$$G_2 = \begin{array}{c} L \\ \swarrow \quad \searrow \\ X \rightarrow Y \end{array} \quad \text{with } \mathbf{L} = L, \mathbf{S} = \emptyset$$

- \mathbf{Z} is an adjustment in MAG $G_{\mathbf{S}}^{\mathbf{L}}$, if (and only if) it is an adjustment in every represented DAG G

- If any of the removed edges of the



corresponds to a non-causal path in any



no adjustment set exists.

- Otherwise, the adjustment criterion works as usual
 \Rightarrow all algorithms for adjustment can be used on MAGs
- Correspondence testable in $O(|\text{children of } \mathbf{X}|(n + m))$

Conclusion

- We have shown an equivalence between separators and adjustment sets
- We provide a collection of algorithms that
 - solve the problems of
 - verifying
 - finding
 - enumerating
 - arbitrary, minimal and minimum
 - d-separators in DAGs
 - m-separators in AGs
 - adjustment sets in DAGs and MAGs
 - are easy to implement

Questions?

Bibliography I

-  Silvia Acid and Luis M. de Campos.
An algorithm for finding minimum d-separating sets in belief networks.
In Proceedings of UAI 1996, pages 3–10, 1996.
-  Judea Pearl.
Causality.
Cambridge University Press, 2009.
-  Thomas Richardson and Peter Spirtes.
Ancestral graph markov models.
Annals of Statistics, 30:927–1223, 2002.
-  Ilya Shpitser.
Appendum to on the validity of covariate adjustment for estimating causal effects, 2012.
unpublished manuscript.

Bibliography II



Ilya Shpitser, Tyler VanderWeele, and James Robins.

On the validity of covariate adjustment for estimating causal effects.

In *Proceedings of UAI 2010*, pages 527–536. AUAI Press, 2010.



Ken Takata.

Space-optimal, backtracking algorithms to list the minimal vertex separators of a graph.

Discrete Applied Mathematics, 158:1660–1667, 2010.



Johannes Textor and Maciej Liškiewicz.

Adjustment criteria in causal diagrams: An algorithmic perspective.

In *Proceedings of UAI*, pages 681–688, 2011.

Bibliography III



Jin Tian, Azaria Paz, and Judea Pearl.

Finding minimal d-separators.

Technical Report R-254, University of California, Los Angeles,
1998.